

# Darwin Mick

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## Education

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B.S.E. Mechanical Engineering

Graduation: May 2022

Ira. A. Fulton Schools of Engineering, Arizona State University

GPA: 3.65

Key Awards and Honors: ASU President's Award; Deans List; Barrett the Honors College

## Technical Skills

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- *Rapid Prototyping*: Precision Machine Training on an Endmill and Lathe, Laser Cutting, 3D-printing
- *Software*: SolidWorks, MATLAB, NX, Python, Gazebo, and ROS

## Research and Experience

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**DREAMS Lab – Autonomous Exploration Systems Research**

**August 2020 – Present**

*Rapid Prototyping Specialist*

- Aided in development and construction of drone deployable soil probes with autorotating propellers
- Designed and fabricated camera and sensor mounts for hex-rotor drones
- Consulted by team members to prototype design solutions with quick turn-around time

**NASA - Jet Propulsion Laboratory**

**January 2019 – August 2019**

*Research Intern*

- Barefoot Project: A machine learning task using a robotic testbed wheel to analyze terramechanics
  - Operated and refined project testbed procedures for data collection
  - Acted as liaison between the testbed hardware team and the project's machine learning customer
  - Designed and fabricated a braking mechanism for robotic testbed automation
  - Designed, assembled, and tested a new electronics assembly for the testbed
- Rendered a CAD storyboard of in-space telescope assembly presented to NASA's science directorate

**BIRTH Lab - Space Mobility Research**

**May 2018 – Present**

*Undergraduate Researcher*

- Implemented ROS to create a controller for a novel robotic excavation and mobility system
- Designed a functional air-tight testbed consisting of 150 parts within a \$3500 budget
- Conducted trade studies to make objective design decisions and choose professional vendors
- Wrote proposals for novel rover ideas to procure funding from NASA for continued development

## Relevant Coursework

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**Autonomous Exploration Systems**

**January 2020 – May 2020**

- Implemented ROS and computer vision techniques to enable autonomous drone flight
- Built models in Gazebo to effectively simulate an autonomous system from start to finish
- Worked on multidisciplinary team to compete in the NSF Cyber-Physical Systems Challenge

**Space Works - NASA Workforce Development**

**January 2018 – December 2019**

- Wrote \$10,000 new technology proposal that was submitted to Marshall Space Flight Center
- Designed and fabricated a craft capable of taking infrared pictures inside a heat chamber

## Publications

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- Thoesen, Andrew, et al. "Comparative performance of granular scaling laws for lightweight grouser wheels in sand and lunar simulant." *Powder Technology* (2020).
- Thoesen, Andrew, et al. "Revisiting Scaling Laws for Robotic Mobility in Granular Media." *IEEE Robotics and Automation Letters* 5.2 (2020): 1319-1325.
- Thoesen, Andrew, et al. "Granular scaling laws for helically driven dynamics." *Physical Review E* 102.3 (2020): 032902.